

W.R.: There are certain equations which are not in Clairaut's form but by a suitable substitution they are reduced to Clairaut's equation.

Ex(1) Solve: $y = 2px + y^2p^3$

Soln. - Given

$$y = 2px + y^2p^3 \quad \text{--- (1)}$$

$$y = \frac{1}{y} (Px + \frac{P^3}{8})$$

Put $y^2 = Y$ and $x = X$ so that

$$2y \frac{dy}{dx} = \frac{dY}{dX} \text{ and } dx = dX$$

$$\Rightarrow y^2 = Px + \frac{P^3}{8}$$

$$\Rightarrow 2yp = \frac{dY}{dX} \Rightarrow 2yp = P \{P = \frac{dY}{dX}\} \Rightarrow Y' = Px + \frac{P^3}{8}$$

$$\Rightarrow p = \frac{P}{2y}$$

which is in Clairaut's form

Eq(1) becomes, $y = 2x \cdot \frac{P}{2y} + y^2 \cdot (\frac{P}{2y})^3$

The general solution is

$$Y = CX + \frac{C^3}{8} \text{ i.e. } y^2 = CX + \frac{C^3}{8} \quad \text{--- (2)}$$

$$\Rightarrow y = \frac{P \cdot x}{y} + y \cdot \frac{P^3}{8y^3}$$

To obtain Singular Solution,

$$\Rightarrow \cancel{y = \frac{1}{y} (Px + \frac{P^3}{8})}$$

Diff (2) w.r. to c

$$0 = x + \frac{3C^2}{8} \Rightarrow C^2 = -\frac{8x}{3} \quad \text{--- (3)}$$

Putting these value in (2)

$$y^2 = Cx + \frac{C^2 \cdot C}{8}$$

$$\Rightarrow y^2 = Cx + \frac{C}{8} \cdot (-\frac{8x}{3})$$

$$\Rightarrow y^2 = \frac{3Cx - Cx}{3} = -\frac{2Cx}{3}$$

$$\Rightarrow y^4 = \frac{4}{9} C^2 x^2 \quad \{ \text{Squaring} \}$$

$$\Rightarrow y^4 = \frac{4}{9} x^2 \times (-\frac{8x}{3}) \quad \{ \text{from (3)} \}$$

$$\Rightarrow y^4 = -\frac{32x^3}{27}$$

$$\Rightarrow 27y^4 + 32x^3 = 0$$

This is the Singular Solution.

Ex(2) Solve: $x^2 \left(y - x \frac{dy}{dx} \right) = y \left(\frac{dy}{dx} \right)^2$

Soln:- Given, $x^2 (y - xp) = y p^2$ — (i)

~~$\Rightarrow x^2 y - x^3 p = y p^2$~~
 ~~$\Rightarrow x^2 y = x^3 p + y p^2$~~

Put $x^2 = X$ and $y^2 = Y$ so that

$2x dx = dX$ and $2y dy = dY$

$\therefore \frac{dY}{dX} = \frac{2y dy}{2x dx} \Rightarrow \frac{Y}{X} p - p \Rightarrow p = \frac{pX}{Y} \left\{ p = \frac{dY}{dX} \right\}$

Putting the value of p in (i)

$x^2 \left(y - x \cdot \frac{pX}{Y} \right) = y \cdot \left(\frac{pX}{Y} \right)^2$

$\Rightarrow x^2 \left(\frac{y^2 - pX^2}{Y} \right) = \frac{Y \times p^2 X^2}{Y}$

$\Rightarrow x^2 (y^2 - x^2 p) = x^2 p^2$

$\Rightarrow y^2 = x^2 p + p^2$

$\Rightarrow Y = PX + P^2$ — (ii) {which is in Clairaut's form}

$\therefore$ The general solution is

$Y = CX + C^2$ — (iii) $\Rightarrow y^2 = Cx^2 + C^2$ — (iv)

In order to find singular solution, Roots of C be equal

$\therefore b^2 - 4ac = 0$

$\Rightarrow (x^2)^2 - 4 \times 1 \times (-y^2) = 0$ $\{ C^2 + Cx^2 - y^2 = 0 \}$

$\Rightarrow x^4 + 4y^2 = 0$

Which is called singular solution

Ex(3) Solve: $(px - y)(x - py) = 2p$

Soln: Do yourself.

Put $x^2 = X$ and $y^2 = Y$

Ans: — (i) The general solution: $y = Cx - \frac{2C}{1-C}$
The Singular Solution

#4 Trajectories of a family of Curves

#4.1 Definition

Trajectory :- A Curve which cuts every member of a given family of curves according to a given rule is called a trajectory of the given family.

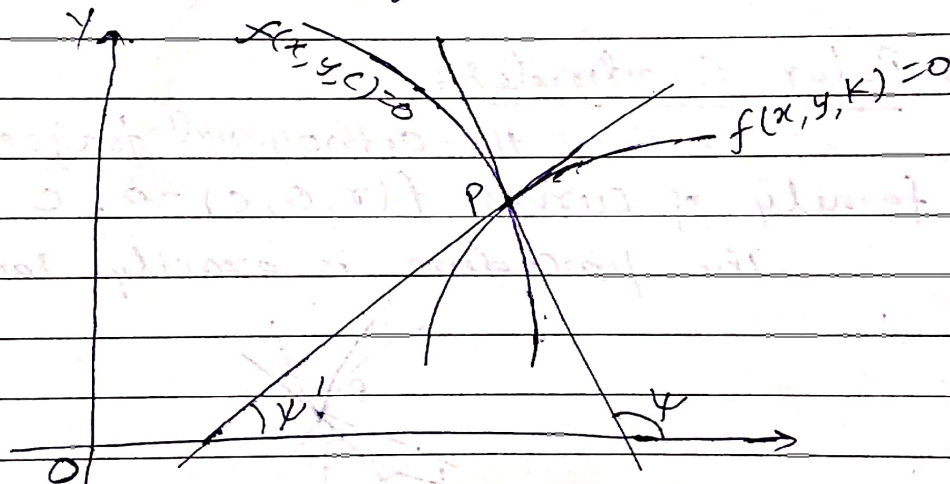
Every member of a given family of curves at a constant angle.

Orthogonal Trajectories :- If a constant angle is a right angle, then the trajectory is said to be orthogonal.

#4.2 Orthogonal Trajectories :-

(i) Cartesian co-ordinates :-

To Find the orthogonal trajectories of the family of curves $f(x, y, c) = 0$; c being a parameter.



The equation of the Curve, $f(x, y, c) = 0$ — (i)

Diff. (i) w.r. to x and eliminating c between (i) and the derived result.

Let the diff. eq. be $\phi(x, y, \frac{dy}{dx}) = 0$ — (ii) {using (i)}

Let $F(x, y, k) = 0$ be the equation of the Curve which cuts the given family $f(x, y, c) = 0$ at a constant angle α .

Let P be the point of their intersection.

Let $m = \tan \psi = \frac{dy}{dx}$ and m' denotes the slope of tangents to the curves $f(x, y, c) = 0$ and $F(x, y, k) = 0$ resp.

Then, $\tan \alpha = \frac{m - m'}{1 + mm'}$ — (iii)

If $\alpha = 90^\circ$, if the trajectories are orthogonal

then, $mm' = -1$

$$\rightarrow m' = -\frac{1}{m} = -\frac{1}{\frac{dy}{dx}} = -\frac{dx}{dy}$$

Thus, If $\frac{dy}{dx}$ is the slope of tangent of the given family of curves, then the slope of the trajectories would be $-\frac{dx}{dy}$.

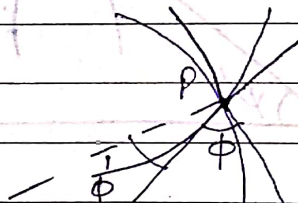
working rule: (i) Diff. the eqⁿ and eliminate the Constant term

(ii) Replace $\frac{dy}{dx}$ by $-\frac{dx}{dy}$

(iii) Integrate the diff. eq, thus obtained and the the solution will be the required eqⁿ of orthogonal Trajectories.

(2) Polar Coordinates:-

To Find the orthogonal trajectories of the family of curves $f(r, \theta, c) = 0$, c being a parameter. The procedure is exactly same as Cartesian case.



$f(r, \theta, c) = 0$

working rule:- (i) Diff. the equation and eliminate the Constant term

(ii) Replace $\frac{dr}{d\theta}$ by $-r^2 \frac{d\theta}{dr}$

(iii) Integrate the new diff. eqⁿ thus obtained and the solution will be required eqⁿ of the orthogonal trajectories.